COURSE DESCRIPTION CARD - SYLLABUS

Course name
Nonlinear control theory [S2AiR2-SW>NTS]

Course

Field of study
Automatic Control and Robotics

Year/Semester
1/1

Area of study (specialization)
Vision Systems

Profile of study
general academic

Level of study
second-cycle

Course offered in
polish

Form of study
full-time

Requirements
compulsory

Number of hours

Lecture
30

Laboratory classes
15

Other (e.g. online)
0

Tutorials
0

Projects/seminars
15

Number of credit points
4,00

Coordinators

dr inż. Bartłomiej Krysiak
bartlomiej.krysiak@put.poznan.pl

Lecturers

prof. dr hab. inż. Przemysław Herman
przemyslaw.herman@put.poznan.pl

dr inż. Bartłomiej Krysiak
bartlomiej.krysiak@put.poznan.pl

dr inż. Marcin Nowicki
marcin.nowicki@put.poznan.pl

Prerequisites

Course objective

Course-related learning outcomes

Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows:

Programme content
none

Teaching methods
none

Bibliography
none

Breakdown of average student's workload

	Hours	ECTS
Total workload		
Classes requiring direct contact with the teacher		
Student's own work (literature studies, preparation for laboratory classes/ tutorials, preparation for tests/exam, project preparation)		